

The logo for the Utah Department of Transportation (UTDOT) features the letters "UTDOT" in a bold, blue, sans-serif font. The "U" and "T" are connected, as are the "D" and "O".

 *Keeping Utah Moving*



Six Trends Transforming Transportation

Blaine D Leonard, P.E., D.GE., F.ASCE
ITS Program Manager
Utah Dept of Transportation

Chair, AASHTO Connected and Automated
Vehicles Technical Working Group



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In the future, transport networks
will think for themselves.



Tomorrow will be nothing like today.

www.hsbc.com/inthefuture

HSBC 



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The coming change in transportation automation will be as significant as the transition from horses to horsepower



Everything will change:

- How we drive
- What we drive
- If we drive
- Who "drives"
- What we own
- What we share



Demographic Trends

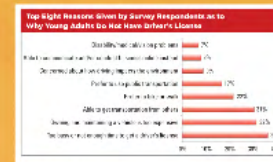
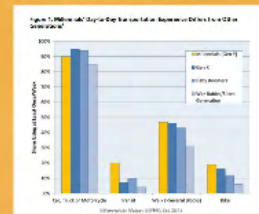
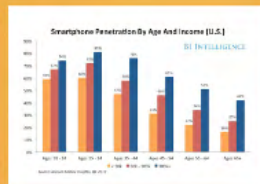
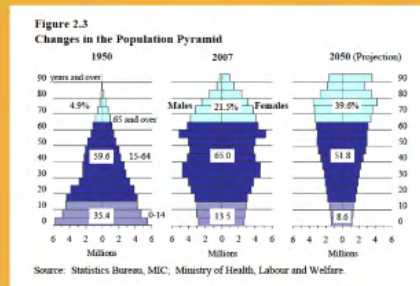
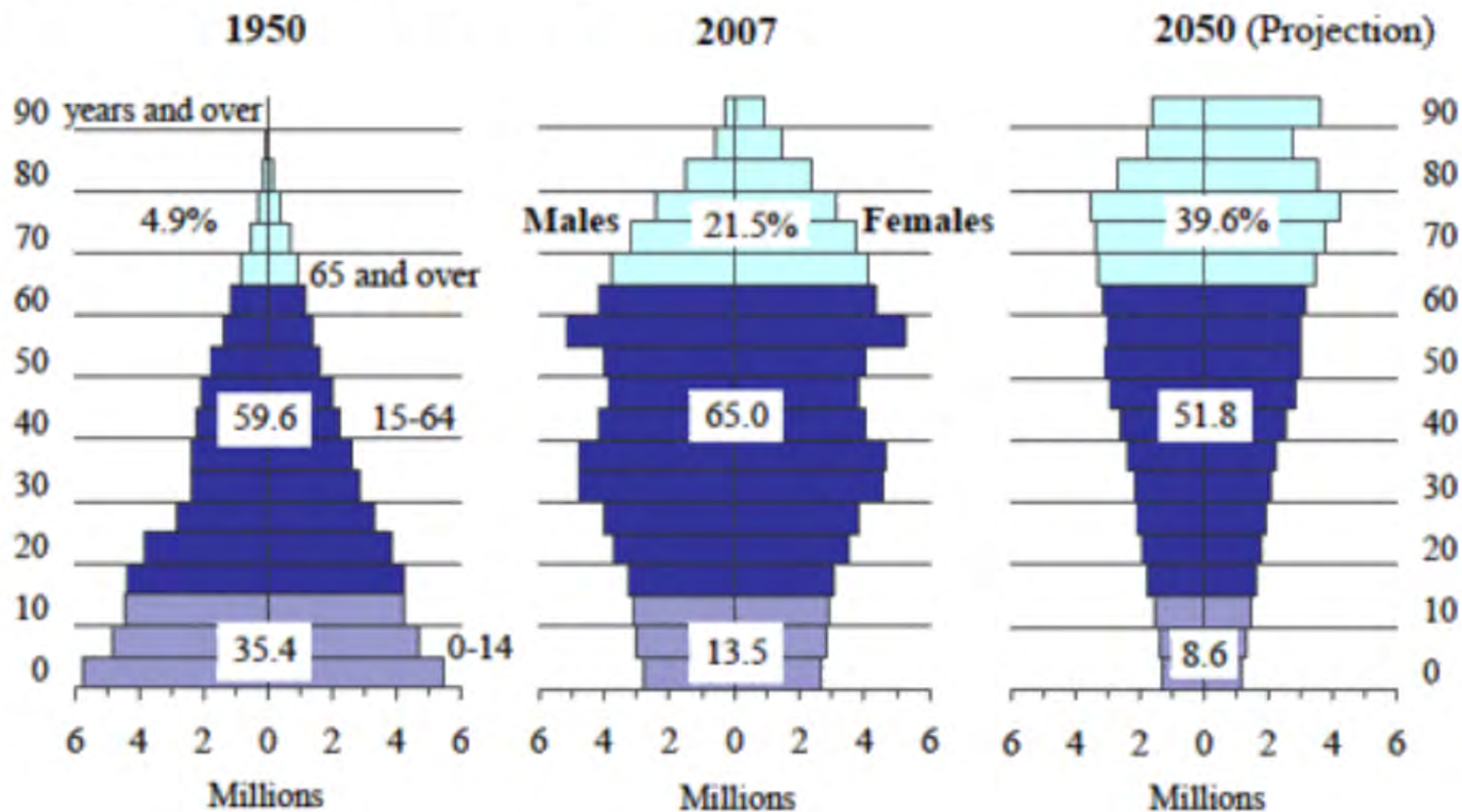
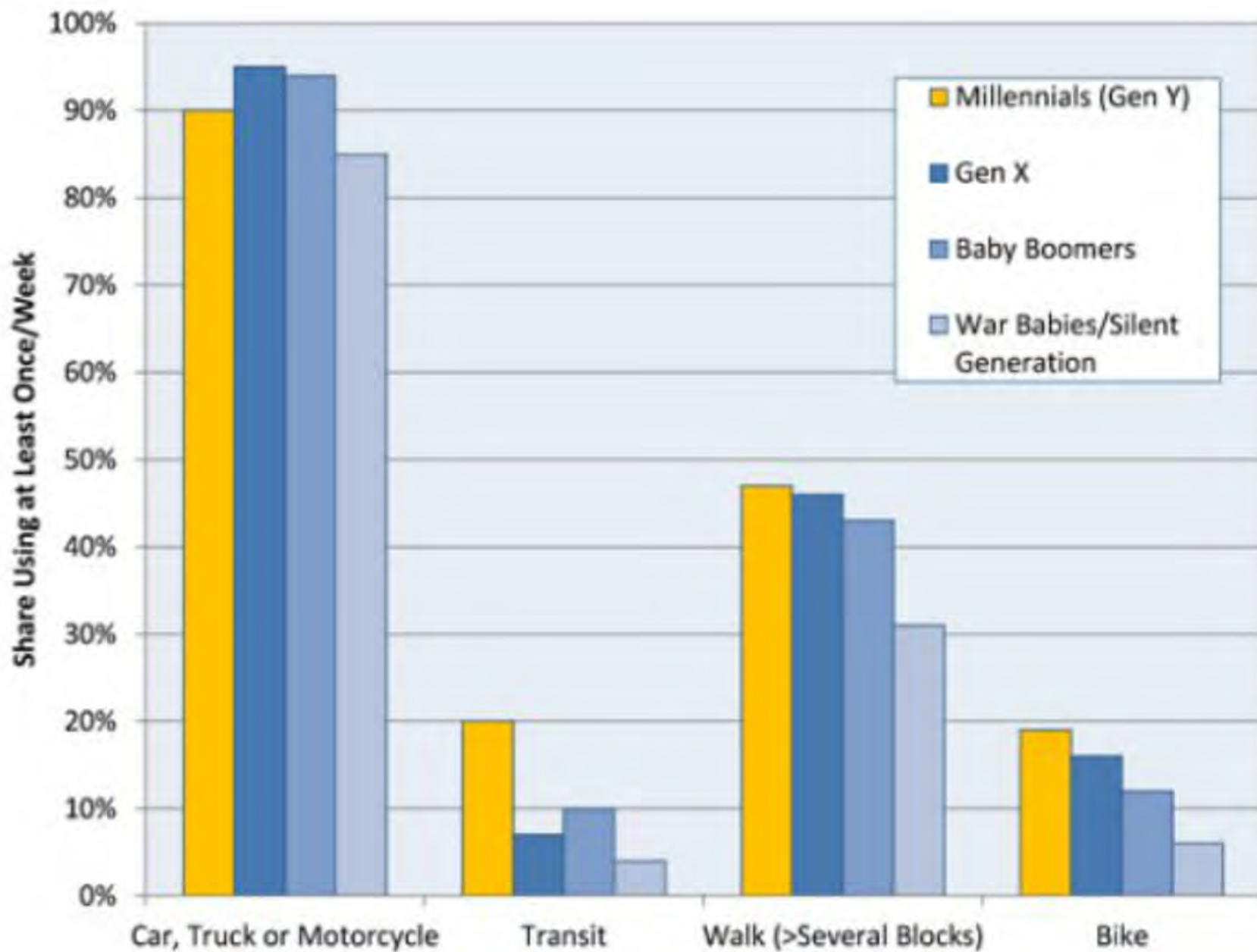


Figure 2.3
Changes in the Population Pyramid

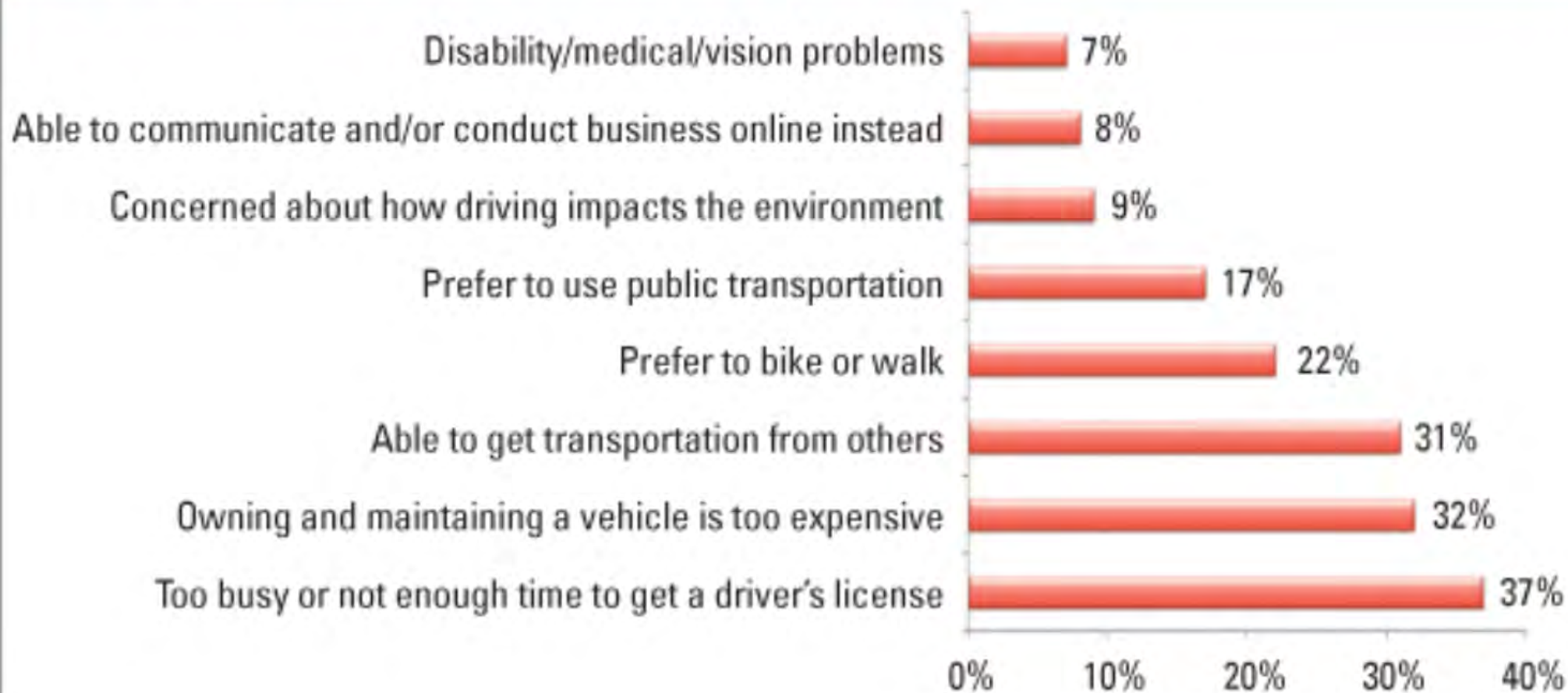


Source: Statistics Bureau, MIC; Ministry of Health, Labour and Welfare.

Figure 1. Millennials' Day-to-Day Transportation Experience Differs from Other Generations⁷



Top Eight Reasons Given by Survey Respondents as to Why Young Adults Do Not Have Driver's License



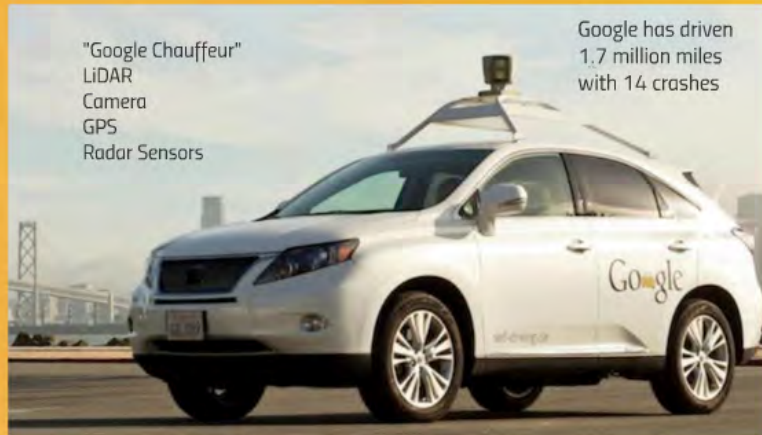
Big Data







Autonomous (Self Driving) Vehicles



"Google Chauffeur"
LiDAR
Camera
GPS
Radar Sensors

Google has driven
1.7 million miles
with 14 crashes



Driving factors:
- safety
- reduced energy use

Issues with autonomous vehicles:
- security
- reliability
- liability / insurance
- extreme light and dark
- nuances of the law
- application of artificial intelligence



Existing Automated Applications:

- Parallel Parking Assist
- Lane Departure Warnings
- Adaptive Cruise Control ("Traffic Jam" Driving)
- Collision Warning



"By the time we get to the autonomous vehicle, it won't be that big of a deal"
- Bill Ford, Executive Chairman, Ford Motor Co

Incremental vs. Disruptive Technology



Vehicles

"Google Chauffeur"

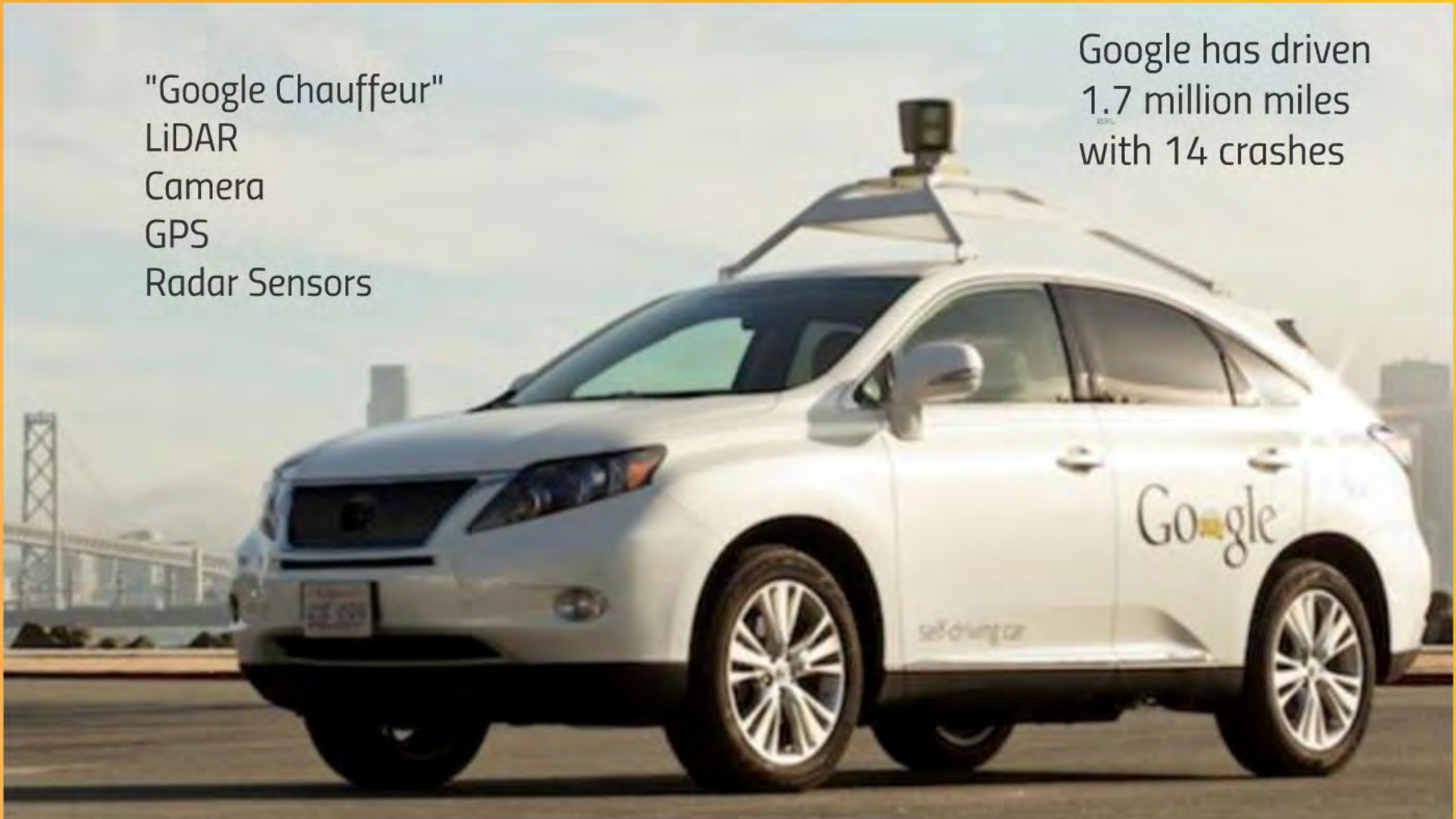
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Existing Automated

- Parallel Parking

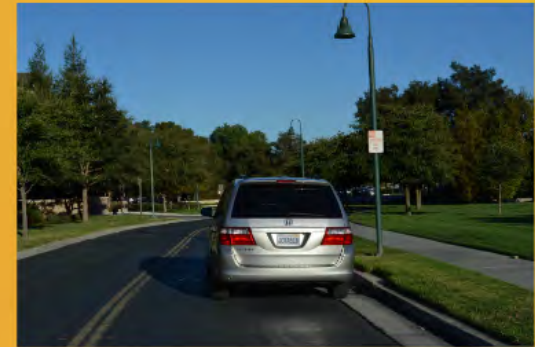


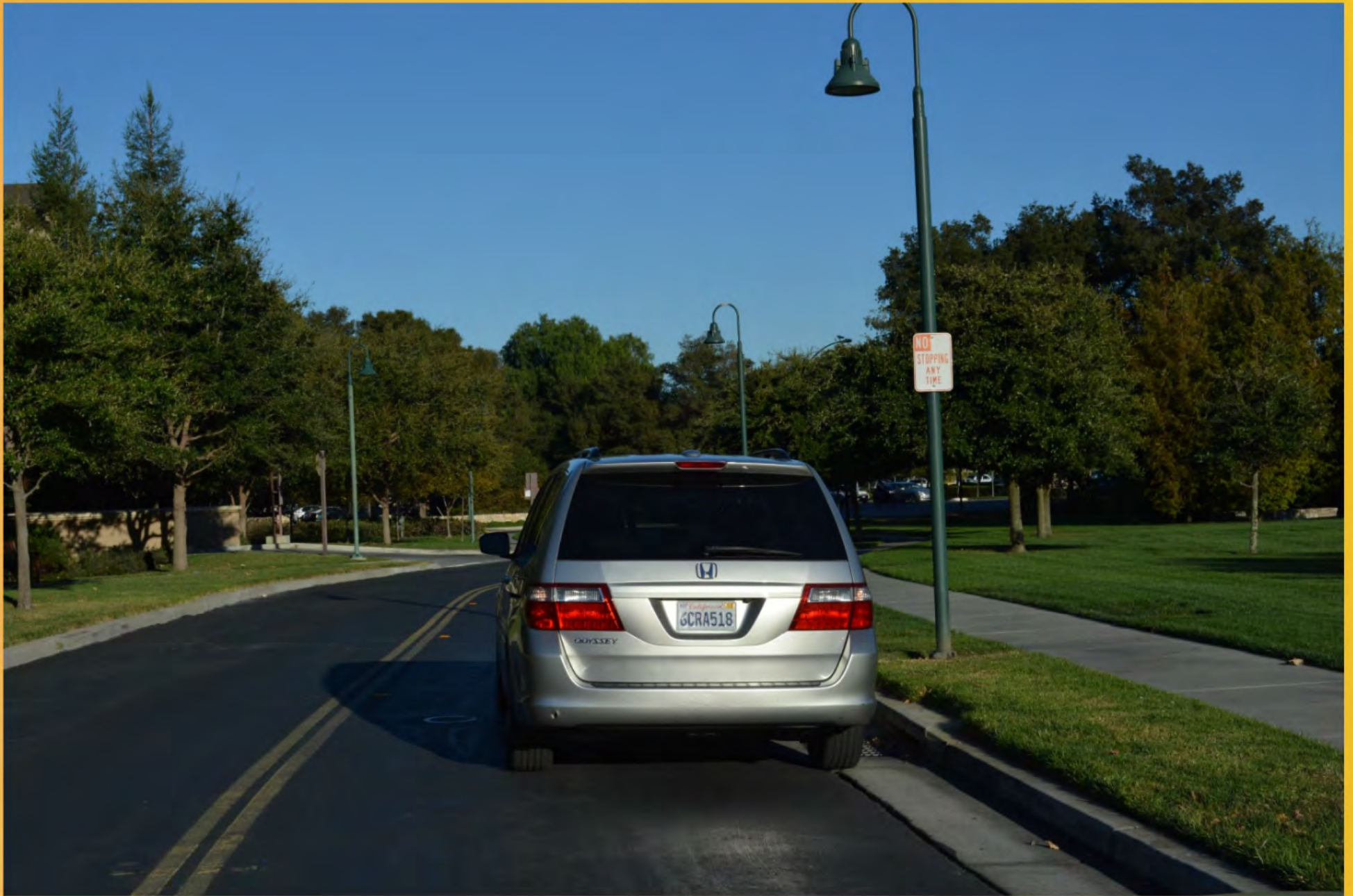
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"Connected"



Connected Vehicles

Vehicles communicate with:

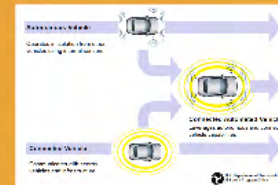
- other vehicles
- infrastructure
- pedestrians / bicyclists, etc.



Automated vehicles "see"



Connected vehicles "learn"

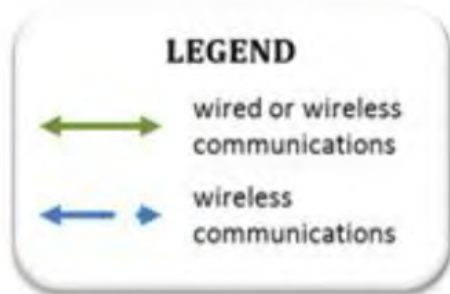


"Connected"

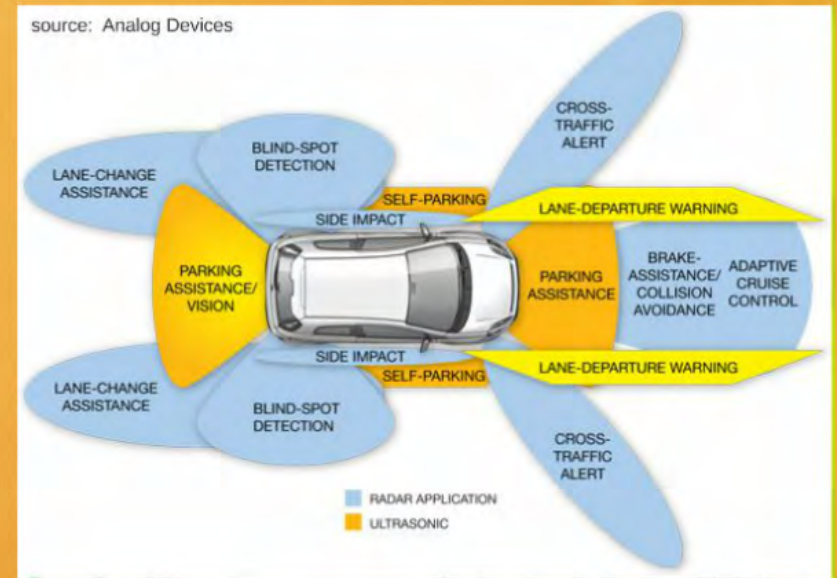
Will our cars be smarter than smartphones?

Communication technologies will enable ubiquitous connectivity to the internet from car dashboards.

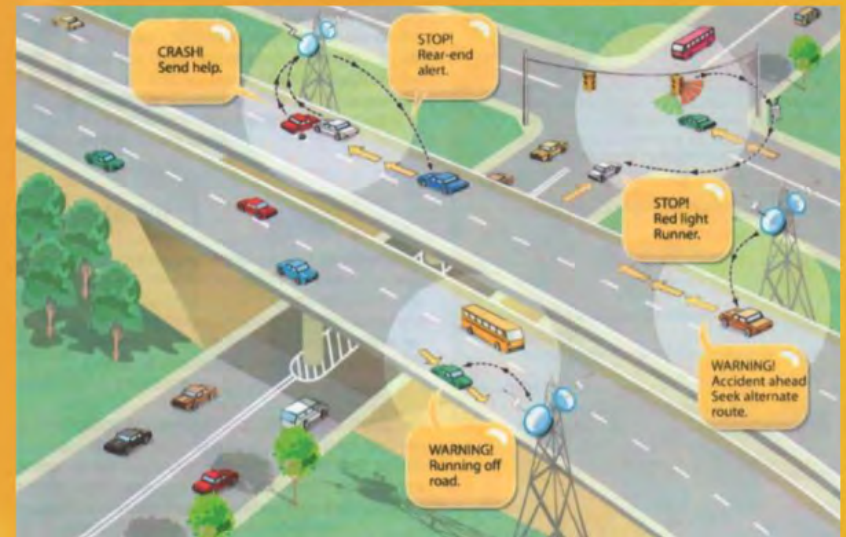




Automated vehicles "see"



Connected vehicles "learn"



Autonomous Vehicle

Operates in isolation from other vehicles using internal sensors



Connected Automated Vehicle
Leverages autonomous and connected vehicle capabilities

Connected Vehicle

Communicates with nearby vehicles and infrastructure



Mobility



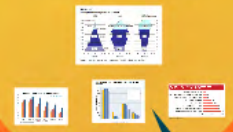
Vehicle Propulsion







Demographic Trends



Big Data



Vehicle Propulsion



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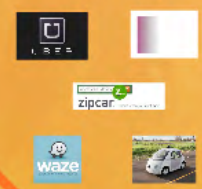


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Autonomous (Self Driving) Vehicles



Mobility

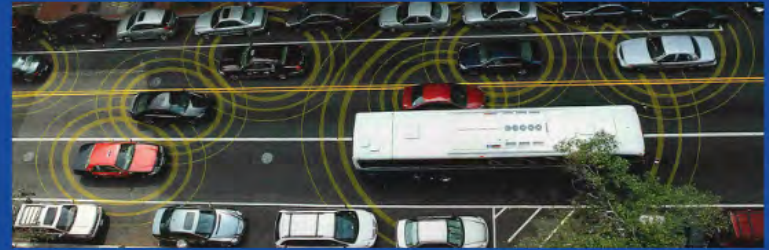


Connected Vehicles



UTDOT

Keeping Utah Moving



Six Trends Transforming Transportation



Planning in Times of Rapid Change

Jeff Harris
Planning Director



Disruptive Change

- Rapid and disruptive change causes uncertainty
- Uncertainty leads to greater risk and, yes, potential opportunity
- With high uncertainty, traditional methods of strategy development fail

Traditional Transport Planning Framework

- Fact-based approach
- Assumes a deep analytical understanding of today is the key to understanding the future
 - Past trends
 - Population and employment
 - Travel demand
 - Mode split
 - Capacity, or supply
 - Land-use
 - Results in a single point forecast of future condition

A New Transportation Planning Framework

- Avoid binary approach
 - Do nothing
 - Continue with traditional approach
- Must understand the uncertainty we are facing
 - Not burying it in meaningless base forecasts, or avoiding analysis
 - Embrace it, slice it, dice it, explore it, and get to know it
 - Separate the unknown from the unknowable - residual uncertainty
- New tools - an adaptive approach
 - Pick the tool(s) that matches the level of uncertainty
 - Scenario planning
 - We do know certain things
 - Bounding range of possibilities